

Using the MATLAB software package perform each of the following tasks:

1. Solve Q6 and Q7 of Assignment No.1 by employing the MATLAB functions **cp2tform** and **tformfwd**.

cp2tform

TFORM = cp2tform (input_points, base_points, *transformtype*) takes pairs of reference points and uses them to infer a spatial transformation. input_points is an *m*-by-2 double matrix containing the *x*- and *y*-coordinates of reference points in the system one want to transform. base_points is an *m*-by-2 double matrix containing the *x*- and *y*-coordinates of reference points are *m*-by-2 double matrix containing the *x*- and *y*-coordinates of reference points specified in the base system. *transformtype* specifies the type of spatial transformation to infer. Some supported transformations are 'nonreflective similarity', 'similarity', 'affine' and 'projective'.

tformfwd

Transformed_Data = tformfwd (TFORM, Data) applies the 2D spatial transformation defined in TFORM to the matrix Data yielding the matrix Transformed_Data. Data is an n-by-2 double matrix containing the x- and y-coordinates of points in the system you want to transform.

2. Solve Q4 of Assignment No.3 utilizing the MTLAB function **normxcorr2**.

normxcorr2

C = normxcorr2 (template, A) computes the normalized cross-correlation of the matrices template and A. The matrix A must be larger than the matrix template for the normalization to be meaningful. The resulting matrix C contains the correlation coefficients, which can range in value from -1.0 to 1.0.

3. Given below the pixel coordinates of five points in the left image of the stereopair of Lab. No.1. Given also the approximate pixel coordinates of their conjugates in the right image. Determine their correct pixel coordinates using the MTLAB function **normxcorr2**.

Point	Left Coordinates		Right Coordinates (Approximate)		
No.	С	r	с'	r'	
1	2535	3535	337	3502	
2	2740	961	516	938	
3	3752	1787	1537	1754	
4	4684	932	2439	907	
5	4765	4437	2585	4413	